Integrated ADC for Altera Cyclone-IV Devices

This Technical Brief describes how to use Delta Sigma Modulation to implement resource-efficient Analog-to-Digital Converters (ADC) in Altera FPGA devices. Starting with an introduction into the technology of Delta Sigma Modulation, we will cover the relevant technical aspects for implementing and applying this as a flexible and cost-efficient means for ADC. We will provide the results of diligent testing using Altera Cyclone-IV FPGA devices which led to our technical specifications (Signal-to-Noise Ratios, Linearity, Spurious-Free Dynamic Range values).
Field-Programmable Gate-Arrays (FPGA) are well established for implementing programmable logic. A lesser known feature is their programmable digital I/O capabilities. Supporting Low-Voltage Differential Signaling (LVDS) at frequencies of many hundred MHz, FPGA pins have become a viable option for quality analog I/O. This Technical Brief shows how to implement Delta Sigma Analog-to-Digital Converters (ADC) inside Altera FPGA devices plus some additional passive components.

The result is a flexible integrated solution with smaller PCB footprint, field-upgradability and reduced risk of device obsolescence.

Key Features

- SNR 60 dB (compares to 10 bits effective resolution)
- Sample-rate up to 500 k samples per second
- Input range 0 to 3.3 V with high linearity
- Cost-efficient for multi-channel-systems
- Resources < 200 LEs for Altera Cyclone-IV

Areas of Applicability

- Flexible data acquisition systems
- Solution for “one more IO”-problems
- Integrated voltage monitoring system
- Instrumentation and control systems
- Sensor input in ambient intelligence
- Integrated microcontrollers with reduce risk of parts obsolescence

The integrated ADC technology presented in this Technical Brief has undergone extensive testing and diligent analysis and has demonstrated to be robust and of high quality. When combined with the appropriate design methodology it is considered application-ready.
Concept

The basic theory behind the Delta Sigma Modulation is shown in Fig. 1. The time-continuous signal $x(t)$ is the input signal and the resulting output is the time-discrete digital $y(z)$. A First-Order Delta Sigma Modulator comprises a feedback loop which subtracts the feedback signal from the input signal (delta). These differences are then summed up in the integrator (sigma).

$$
H(z)_{\text{signal}} = \frac{1}{1 + z^{-1}}
$$

This feedback loop leads to the transfer functions of the First-Order Delta Sigma Modulator: $H(z)_{\text{signal}} = 1; H(z)_{\text{noise}} = 1 - z^{-1}$. As these functions underline, the noise is high-pass filtered which is convenient looking at the other aspect of the Delta Sigma Modulation, the oversampling. With oversampling, we sample the analog input signal with a much higher frequency than the Shannon-Nyquist theorem demands. The result, in combination with the high-filtering effect of the Delta Sigma Modulator is, that the noise is distributed to the higher frequencies. This is called Noise Shaping. The possible signal-to-noise (SNR) ratio gain using oversampling is 3dB per octave. Using first order Delta Sigma Modulation, this SNR gain rises to 9dB per octave. These effects can be seen in Fig. 2 a, b and c.

Fig. 2a shows the Nyquist Sampling converter. All quantizing noise is in the desired signal band. A first improvement comes from Oversampling and is shown in Fig. 2b. It distributes the noise equally over the sample spectrum. A second improvement is Noise Shaping which is shown in Figure 2c. Noise-shaping acts as a high pass for the noise and is
the enabling piece which allows us to build high quality ADC inside purely digital FPGA devices.

However, the drawback of Noise Shaping is that one must come up with appropriate parameter sets to operate the inherently instable Delta Sigma Modulator.

Parameter Setting

To obtain suitable parameters for the Delta Sigma Modulator, a Matlab simulation was created. The design flow for the parameter creation can be seen in Fig. 3:

When running this parameter search, a parameter space is being searched to find the most suitable parameter set for the desired application. The parameter space addresses the integrator time-constant which is in this case a low-pass time-constant and the sample frequency which determines the oversampling frequency. An exemplary heat map of one of these simulations can be seen in Fig. 4.

The heat-map is plotted by drawing the two different parameters over the resulting SNR value and shows two things. At first, it shows a good parameter set for the desired input frequency. It also shows that just using a higher sample frequency won’t automatically give better results unless you consider the other parameters such as the integrator time-constant.

Implementation

The basic components are shown in Fig. 5. The external components are the two resistors and one capacitor. In combination with the Low Voltage Differential Signaling (LVDS) receiver and a Flip-Flop a Delta Sigma Modulator is built.
The Delta Sigma ADC was implemented using VHDL to support a wide range of target FPGA devices. It consists of several modules, namely the Delta Sigma Modulator which generates the bit-stream, a low-pass filter which cuts off the high band noise and prevents aliasing. The last module is a decimator filter which converts the signal to the desired sample rate and bit width.

**Testing**

To validate the simulation results, diligent analysis was done. In particular we tested and measured the quality of results for Altera Cyclone-IV FPGA devices namely the EP4CE115, which is located on the Terasic Industrial Networking Kit (INK) DE2-115 board.

For example, values for the resistors and the capacitor were picked from simulation, and were determined to be 100 pF for the capacitor and 10 kOhm for the resistors which are values from the parameterization for a 100 MHz bitstream sample rate.

During our tests we found out that the quality of the passive components has little effects on the overall quality of the ADC. For example, the resistors can be wired metal oxide resistors and the capacitor can be a styroflex capacitor. The voltage reference was created by a voltage divider from the 3.3 V Voltage source using two additional 10 kOhm resistors.

**Crosstalk**

Crosstalk is the influence of other ADC channels on the ADC. During our testing we found very little effects of crosstalk: For example, we implemented two Delta Sigma ADC on the same FPGA voltage bank. The measured channel had no input signal, and the other
channel had a full scale 1 kHz input signal. The resulting signal on the channel with no input was measured and the resulting SNR was 2.3 dB.

**Temperature Drift**

For the influence of the temperature drift, we cooled the FPGA as well as the external circuitry down to a temperature of -40 °C and then back to room temperature. We could not detect any effects caused by temperature drift.

**Linearity**

For linearity analysis an input signal was sampled and the resulting digitized bit stream was recorded using the Altera Signaltap integrated logic analyzer.

The measured sample depth was 65536 Samples. The clock speed of the Delta Sigma Modulator was 100 MHz. The example schematic can be seen in Fig. 6. To analyze the linearity, voltages from 0 to 3.3 Volts were generated using an Agilent E3642A power supply. These voltages were verified using an Agilent 33410A high performance multimeter. The whole measurement was controlled by a Linux PC using the GPIB interfaces of the Voltage Source and the Multimeter. The results of the linearity measurement can be seen in Fig. 7. The integrated nonlinearity (INL) plot demonstrates linearity over the entire voltage input range, as well as a strongly monotonic behavior. It also shows that the whole range from 0V to 3.3 V can be measured.
Quality of Results

Other important parameters of an ADC are the Signal to Noise Ratio (SNR), the Spurious Free Dynamic Range (SFDR) and the Total Harmonic Distortion (THD). These values were measured using the same resistor / capacitor values (10 kOhm and 100 pF, resp.) as during the measurement of the linearity. These parameters have been measured using different input signal frequencies from 500Hz to 15 kHz and a sample frequency of 50 kHz with an oversampling ratio of 1024. The calculation of the SNR, the SFDR and the THD was done using Matlab.

<table>
<thead>
<tr>
<th>Frequency (Hz)</th>
<th>SNR (dB)</th>
<th>THD (%)</th>
<th>SFDR (dB)</th>
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<tbody>
<tr>
<td>500</td>
<td>59</td>
<td>0.02</td>
<td>38</td>
</tr>
<tr>
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<tr>
<td>15000</td>
<td>53</td>
<td>0.01</td>
<td>53</td>
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Fig. 8 shows a Fourier spectrum with a good parameter set for the Delta Sigma Modulator. In this Fourier spectrum the 60dB SFDR can be easily seen.

Resource Requirements

The resource usage of the particular Altera Cyclone-IV design used in the analysis was 192 LEs plus one M9K memory element.

The main resources are needed by the filtering stage, the actual Delta Sigma Modulator just uses 1 LE. The standard input voltage range is from 0V to the full feedback pin voltage.
It can be extended by using an op-amp to scale the input signal, or by changing the input resistor to a higher value.

Of course, when a higher input voltage is applied, measures should be taken to protect the FPGA input pin from over-voltage. One can achieve high quality of ADC results without high quality passive components for the Delta Sigma Modulator. This is an additional benefit of this method. The only requirements are that the integrator time-constant is matching the values calculated in the simulation.
Figure 8: Example Fourier spectrum of a 1kHz sine tone
References


