

# TCP/IP for Real-Time Embedded Systems The Good, The Bad, The Ugly



### MLE Mission: "From Software to Silicon!"

High-Performance (Embedded) Compute & Connected Systems-of-Systems need "Offload Engines" for better performance, lower and deterministic latency and improved energy efficiency.

Focus on standards such as PCIe, NVMe, Ethernet, TCP/UDP/IP, TSN.



#### Multi-Gigabit Real-Time Networking Market & Technology Forces

6G Radio Integrated Communication and Sensing (ICAS) Zone-Based In-Vehicle Networking (Auto/TSN)

#### 100G Real-time Backbone for Virtualized PLC (Robo/TSN)









### Work Motivation

#### Systems-of-systems

- Al inference using high-data-rate sensors (Camera, Radar, Lidar)
- Tightly-coupled: i.e. distributed processing with microservices
- Loosely-connected via networks (which continuously are the bottleneck)

Need to optimize

- for power / energy efficiency
- for throughput
- for (deterministic) latency and real-time delivery

#### Domain-Specific Architectures:

- "Offload" (protocol) processing but yet adhere to (defacto) standards and APIs
- Make networks more deterministic and Time-Sensitive



# TCP - The Good

- Very well known protocol, mature (50 year anniversary)
- Reliable, scalable, packet transport
- Ubiquitous use in networking: LAN, WAN, WiFi, 3GPP mobile
- Stream-based with backpressure
  - ⇒ Allows to implement self-synchronized dataflow processing systems





# TCP - The Bad

- Large compute burden for TCP in SW
- Different behavior across different implementations

• However, TOEs (TCP Offload Engines) and TCP Full Accelerators exist





### Netperf TCP\_STREAM Results - CPU Load



Tx Side

**Rx Side** 



# Netperf TCP\_STREAM Results: Efficiency



Tx Side

Rx Side



# Benefits of PC-Side TCP Full Accelerators

#### With PC-side TCP Full Accelerators:

- All PC CPU cores can fully be used for sensor data processing
- Round-trip time (RTT) is minimal, so only small Tx buffers are needed in the sensor-side FPGA
- All data streams between sensor and server can be prioritized using QoS, scheduling, traffic shaping etc
- Optional in-network processing with IEEE 1588-2019 HA PTP

#### **Unaccelerated PC:**

- Precious CPU cores are consumed for network protocol processing
- Round-trip time (RTT) is high which eats up BRAM resources in the sensor-side FPGA
- TCP scheduling and congestion control restricted to Operating System capabilities







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1. TCP Byte Streams, cont'd		
Sender (messages) Head-of-line blocking: Short messages can get stud High tail latency	TCP (stream)	
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#### **2. TCP is Connection-Oriented**

#### Requires long-lived state for each stream

- ~2000 bytes per connection in Linux, not including packet buffers
- Individual datacenter apps can have thousands of connections
- Mitigate with connection pooling/proxies (e.g. Facebook)? Adds overhead
- Challenging for NIC offloading (e.g. Infiniband): thrashing in connection caches

#### Before sending any data, must pay round-trip for connection setup

- Problematic in serverless environments: can't amortize setup cost
- Motivation for connections:
  - Enable reliable delivery, flow control, congestion control
  - But, all these can be achieved without connections



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#### **3. TCP Uses Fair Scheduling**

- When loaded, share bandwidth equally among active connections
- Well-known to perform poorly: everyone finishes slowly
- Run-to-completion approaches (e.g. SRPT) are better
  - But requires message sizes



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#### 4. TCP: Sender-Driven Congestion Control

#### • Senders responsible for scaling back transmission rates when needed

- But, they have no direct knowledge of congestion
- Congestion signals based on buffer occupancy:
  - Packets dropped if queues overflow
  - Congestion notifications based on queue length

#### • Problems:

- Significant buffer occupancy when system is loaded
- Queuing causes delays, especially for short messages



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#### 1. Homa is Message-Based

- Dispatchable units are explicit in the protocol
- Enables efficient load balancing
  - Multiple threads can safely read from a single socket
  - Future NICs can dispatch messages directly to threads
- Enables run-to-completion (e.g. SRPT)

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#### 2. Homa is Connectionless

- Fundamental unit is a remote procedure call (RPC)
  - Request message
  - Response message
  - RPCs are independent

#### No long-lived connection state

- (But there is long-lived per-peer state: ~200 bytes)
- No connection setup overhead •
  - Use one socket to communicate with many peers

#### Homa ensures end-to-end RPC reliability

No need for application-level timers



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#### Homa

- "peacefully co-exists with TCP
- behaves better in congested networks

MLE is implementing a Homa Accelerator <u>R</u>apid, <u>R</u>eliable, <u>R</u>equest-<u>R</u>esponse <u>P</u>rotocol (Quad-R P)



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